Data sheet



SIPLUS ET 200SP CPU 1515SP PC2 F based on 6ES7677-2SB42-0GB0 with conformal coating, -40...+60 °C, 8 GB RAM, 128 GB CFast with Windows 10 IoT Enterprise 64-bit and S7-1500 Software Controller CPU 1505SP F preinstalled, interfaces: 1x slot CFast, 1x slot SD/MMC, 1x connection for ET 200SP BusAdapter PROFINET, 1x 10/100/1000 Mbps Ethernet 2x USB 3.0; 2x USB 2.0, 1x DisplayPort, documentation on USB flash drive, restore USB flash drive

Figure similar

General information	
Product type designation	CPU 1515SP PC2 F
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	see entry ID: 109746275
Installed software	
 Visualization 	No
Control	S7-1500 Software Controller CPU 1505SP F
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms
Input current	
Current consumption (rated value)	1.8 A; Full processor load, incl. ET 200SP modules and using USB
Current consumption (in no-load operation), typ.	0.5 A
Current consumption, max.	2.9 A
I²t	0.426 A ² ·s; with starting current inrush
Power	
Active power input, max.	43 W; incl. ET 200SP modules and using USB
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	16 W
Processor	
Processor type	Intel Atom E3940, 1.6 GHz, 4 cores
Memory	
Type of memory	DDR3L
Main memory	8 GB RAM
CFast memory card	Yes; 30 GB flash memory
SIMATIC memory card required	No
Work memory	
• integrated (for program)	1.5 Mbyte
• integrated (for data)	5 Mbyte
• integrated (for CPU function library of CPU Runtime)	20 Mbyte

Load mamon	
Load memory ● integrated (on PC mass storage)	320 Mbyte
Backup	320 IVIDYIC
·	Voc. all moment areas declared retentive
• with UPS	Yes; all memory areas declared retentive
with non-volatile memory	Yes
CPU processing times	
for bit operations, typ.	10 ns
for word operations, typ.	12 ns
for fixed point arithmetic, typ.	16 ns
for floating point arithmetic, typ.	64 ns
CPU-blocks	
Number of elements (total)	6 000; In addition to blocks such as DBs, FBs and FCs, UDTs, global
DD	constants, etc. are also regarded as elements
DB	
Number, max.	5 999; Number range: 1 to 65535
• Size, max.	5 Mbyte
FB	
• Number, max.	5 998; Number range: 1 to 65535
• Size, max.	1 024 kbyte
FC	
Number, max.	5 999; Number range: 1 to 65535
Size, max.	1 024 kbyte
OB	
• Size, max.	1 024 kbyte
 Number of free cycle OBs 	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
 Number of cyclic interrupt OBs 	20
 Number of process alarm OBs 	50
 Number of DPV1 alarm OBs 	3
 Number of isochronous mode OBs 	1
 Number of technology synchronous alarm OBs 	2
Number of startup OBs	100
Number of asynchronous error OBs	4
 Number of synchronous error OBs 	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24; Up to 8 possible for F-blocks
Counters, timers and their retentivity	21, 00 to 0 00000010111 5100000
S7 counter	
Number	2 048
	2 040
Retentivity	V
— adjustable	Yes
IEC counter	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	410 kbyte; For storage in NVRAM; for storage in mass storage 5 242 020 bytes
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
- 5.5. 5.00.0	

Potentivity adjustable	Voc
Retentivity adjustable Retentivity preset	Yes No
Retentivity preset Local data	INU
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	04 kbyte, max. To kb per block
Number of IO modules	8 192
I/O address area	0 192
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All imputs are in the process image
Subprocess images	32 kbyte, All outputs are in the process image
Number of subprocess images, max.	32
Hardware configuration	02
Integrated power supply	Yes
Number of distributed IO systems	20
Number of DP masters	20
• Via CM	1
Number of IO Controllers	
• via PC interfaces	1
Rack	
Modules per rack, max.	64; CPU 1515SP PC + 64 modules + server module
PtP CM	2., 5. 5. 6. 6. 6. 7. Thousand a control modulo
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available
	slots
Time of day	
Clock	
• Type	Hardware clock
 Hardware clock (real-time) 	Yes; Resolution: 1 s
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Clock synchronization	
• supported	Yes
• to DP, master	Yes
 on Ethernet via NTP 	Yes
on Windows clock, slave	Yes
Interfaces	
Number of industrial Ethernet interfaces	2
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Number of RS 485 interfaces	1; Via CM DP module
Number of USB interfaces	4; 2x USB 2.0, 2x USB 3.0 on front side
Number of SD card slots	1
Video interfaces	
Graphics interface	1x DisplayPort
1. Interface	
Interface type	PROFINET
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Number of connections	88
Interface types	
• RJ 45 (Ethernet)	Yes; Via BusAdapter BA 2x RJ45
— Transmission rate, max.	100 Mbit/s
 Industrial Ethernet status LED 	Yes
 Number of ports 	2
 integrated switch 	Yes
BusAdapter (PROFINET)	Yes; Compatible BusAdapter: BA 2x RJ45, BA 2x FC, BA 2x SCRJ (from FS03,
	V2.2), BA SCRJ / RJ45 (from FS03, V3.1), BA SCRJ / FC (from FS03, V3.1), BA 2x LC (from FS03, V3.3), BA LC / RJ45 (from FS03, V3.3), BA LC / FC
	(from FS03, V3.3)
Protocols	
 PROFINET IO Controller 	Yes
PROFINET IO Device	Yes

• SIMATIC communication	Von
SIMATIC communication Open IF communication	Yes
Open IE communication	Yes
Web server	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
— shortest clock pulse	500 μs
— IRT	Yes
— PROFlenergy	Yes
— Prioritized startup	Yes; max. 32 PROFINET devices; if you want to use the "Prioritized startup" functionality in STEP 7 for the PROFINET interface of the CPU, the CPU and the device must be separated by means of a switch (e.g. SCALANCE X205)
 Number of connectable IO Devices, max. 	128
 Of which IO devices with IRT, max. 	64
— of which in line, max.	64
 Number of connectable IO Devices for RT, max. 	128
— of which in line, max.	128
 Number of IO Devices that can be simultaneously 	8
activated/deactivated, max. — IO Devices changing during operation (partner	Yes
ports), supported	
Number of IO Devices per tool, max.	
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, 625 μs 3
Update time for RT	875 μs)
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
PROFINET IO Device	o kbyte
Services	
— Isochronous mode	No
shortest clock pulse	500 μs
— Shoriest clock pulse — IRT	
— PROFlenergy	Yes Yes
Prioritized startup	Yes
— Prioritized startup — Shared device	Yes
Number of IO Controllers with shared device, max. Asset management record.	4 Voc
Asset management record	Yes
2. Interface	late and a d fith a mark interferon
Interface type	Integrated Ethernet interface
automatic detection of transmission rate	Yes
Autonegotiation	Yes
Autocrossing	Yes
Interface types	V. II.
• RJ 45 (Ethernet)	Yes; Integrated
— Transmission rate, max.	1 000 Mbit/s
Industrial Ethernet status LED	No
Number of ports	1
3. Interface	
Interface type	PROFIBUS with CM DP
Interface type Number of connections	1 1 to 1 1200 that our 2.

Industrian toward	
Interface types	
• RS 485	Yes
Protocols	
PROFIBUS DP master	Yes
PROFIBUS DP slave	Yes
SIMATIC communication	Yes
PROFIBUS DP master	
Number of DP slaves, max.	125
Services	
— Equidistance	No
— Isochronous mode	No
Address area	
— Inputs, max.	8 kbyte
— Outputs, max.	8 kbyte
Interface types	
RS 485	
 Transmission rate, max. 	12 Mbit/s
Protocols	
PROFIsafe	Yes
Number of connections	
Number of connections, max.	88
Number of connections reserved for ES/HMI/web	10
 Number of S7 routing paths 	16
Redundancy mode	
Media redundancy	
— MRP	Yes
— MRPD	Yes
Switchover time on line break, typ.	200 ms
Number of stations in the ring, max.	50
SIMATIC communication	30
PG/OP communication	Yes
	Yes
• S7 routing	
S7 communication, as server	Yes
S7 communication, as client	Yes
User data per job, max.	64 kbyte; BSEND/BRCV: 64 KB; PUT/GET: 960 bytes
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
Data length, max.	1 472 kbyte
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Via Windows and PROFINET interface
• HTTPS	Yes; Via Windows and PROFINET interface
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; From SW CPU 1505SP V2.6
OPC UA Server	Yes; Data access (read, write, subscribe), runtime license required
— Application authentication	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— Security policies	Yes; Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	Yes; "anonymous" or by user name & password
Further protocols	
MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32

Drogram clarma	Voc
Program alarms	Yes 40,000
Number of configurable program messages, max.	10 000
Number of simultaneously active program alarms	1 000
Number of program alarms	1 000
Number of alarms for system diagnostics	200
Number of alarms for motion technology objects	160
Fest commissioning functions	Very Parallel online access possible for up to 0 anning systems
Joint commission (Team Engineering) Status block	Yes; Parallel online access possible for up to 8 engineering systems Yes; up to 8 simultaneously
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
Variables	Inputs, outputs, memory bits, DB, times, counters
Number of variables, max.	
of which status variables, max.	200
of which control variables, max.	200
Forcing	200
• Forcing	Yes
Forcing, variables	Inputs, outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
Number of entries, max.	1 000
— of which powerfail-proof	300
Traces	
Number of configurable Traces	4
Memory size per trace, max.	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
MAINT LED Supported technology objects	Yes
	Yes Yes
Supported technology objects	
Supported technology objects Motion Control • Number of available Motion Control resources for	Yes
Supported technology objects Motion Control Number of available Motion Control resources for technology objects	Yes
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	Yes 2 400
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	Yes 2 400 40; per axis
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	Yes 2 400 40; per axis 80; per axis
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	Yes 2 400 40; per axis 80; per axis 160; per axis
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value)	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value)	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of sositioning axes at motion control cycle of 8 ms (typical value) Controller	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of sositioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Highest safety class achievable in safety mode	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	Yes 2 400 40; per axis 80; per axis 160; per axis 80; per external encoder 20; per cam 160; per cam track 40; per probe 15 30 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature

 Low demand mode: PFDavg in accordance with SIL3 	< 2.00E-05
High demand/continuous mode: PFH in accordance with SIL3	< 1.00E-09 1/h
Ambient conditions	
Ambient temperature during operation	
• min.	-40 °C; = Tmin
• max.	Up to 60 $^{\circ}\text{C}$ with max. 32 ET 200SP modules; up to 55 $^{\circ}\text{C}$ with max. 64 ET 200SP modules
 horizontal installation, min. 	-40 °C; = Tmin (incl. condensation/frost)
 horizontal installation, max. 	60 °C; = Tmax
 vertical installation, min. 	-40 °C; = Tmin
vertical installation, max.	50 °C; = Tmax; with max. 32 ET 200SP modules
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	2 000 m
Ambient air temperature-barometric pressure-altitude	Tmin Tmax at 1 140 hPa 795 hPa (-1 000 m +2 000 m)
Relative humidity	
With condensation, tested in accordance with IEC 60068-	100 %; RH incl. condensation / frost (no commissioning in bedewed state),
2-38, max.	horizontal installation
Vibrations	V
Operation, tested according to IEC 60068-2-6 Transport tested according to IEC 60068-2-6	Yes
Transport, tested acc. to IEC 60068-2-6 Charly testing:	Yes
Shock testing	V
• tested according to IEC 60068-2-6	Yes
• tested according to IEC 60068-2-27	Yes
• tested according to IEC 60068-2-29	Yes
Storage/transport, tested acc. to IEC 60068-2-27	Yes
Resistance	
Coolants and lubricants	Variable discaland all develops in the air
 Resistant to commercially available coolants and lubricants 	Yes; Incl. diesel and oil droplets in the air
Use in stationary industrial systems	
 to biologically active substances according to EN 60721-3-3 	Yes; Class 3B2 mold, fungus and dry rot spores (with the exception of fauna); Class 3B3 on request
 to chemically active substances according to EN 60721-3-3 	Yes; Class 3C4 (RH < 75 %) incl. salt spray acc. to EN 60068-2-52 (severity degree 3); *
 to mechanically active substances according to EN 60721-3-3 	Yes; Class 3S4 incl. sand, dust, *
 Against mechanical environmental conditions acc. to EN 60721-3-3 	Yes; Class 3M8 using the SIPLUS Mounting Kit ET 200SP (6AG1193-6AA00-0AA0)
Use on ships/at sea	
 to biologically active substances according to EN 60721-3-6 	Yes; Class 6B2 mold, fungal and dry rot spores (excluding fauna)
 to chemically active substances according to EN 60721-3-6 	Yes; Class 6C3 (RH < 75 %) incl. salt spray acc. to EN 60068-2-52 (severity degree 3); *
— to mechanically active substances according to EN 60721-3-6	Yes; Class 6S3 incl. sand, dust; *
 — Against mechanical environmental conditions acc. to EN 60721-3-6 	Yes; Class 6M4 using the SIPLUS Mounting Kit ET 200SP (6AG1193-6AA00-0AA0)
Usage in industrial process technology	
— Against chemically active substances acc. to EN 60654-4	Yes; Class 3 (excluding trichlorethylene)
 Environmental conditions for process, measuring and control systems acc. to ANSI/ISA-71.04 	Yes; Level GX group A/B (excluding trichlorethylene; harmful gas concentrations up to the limits of EN 60721-3-3 class 3C4 permissible); level LC3 (salt spray) and level LB3 (oil)
Remark	
 Note regarding classification of environmental conditions acc. to EN 60721, EN 60654-4 and ANSI/ISA-71.04 	* The supplied plug covers must remain in place over the unused interfaces during operation!
Conformal coating	
Coatings for printed circuit board assemblies acc. to EN 61086	Yes; Class 2 for high reliability
Protection against fouling acc. to EN 60664-3	Yes; Type 1 protection

 Military testing according to MIL-I-46058C, Amendment 7 Qualification and Performance of Electrical Insulating Compound for Printed Board Assemblies according to IPC-CC-830A 	Yes; Discoloration of coating possible during service life Yes; Conformal coating, Class A
Operating systems	
pre-installed operating system	Windows 10 IoT Enterprise 2016 LTSB, 64bit, MUI
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes; incl. failsafe
— FBD	Yes; incl. failsafe
— STL	Yes
— SCL	Yes
— CFC	No
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
Copy protection	Yes
Block protection	Yes
Access protection	
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Open Development interfaces	
 Size of ODK SO file, max. 	5.8 Mbyte
Peripherals/Options	
SD card	Optionally for additional mass storage
Dimensions	
Width	160 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	0.83 kg

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